



# The Sentinel-3 mission – SST

## *SST data in practice*

Anne O'Carroll, Igor Tomazic, Gary Corlett

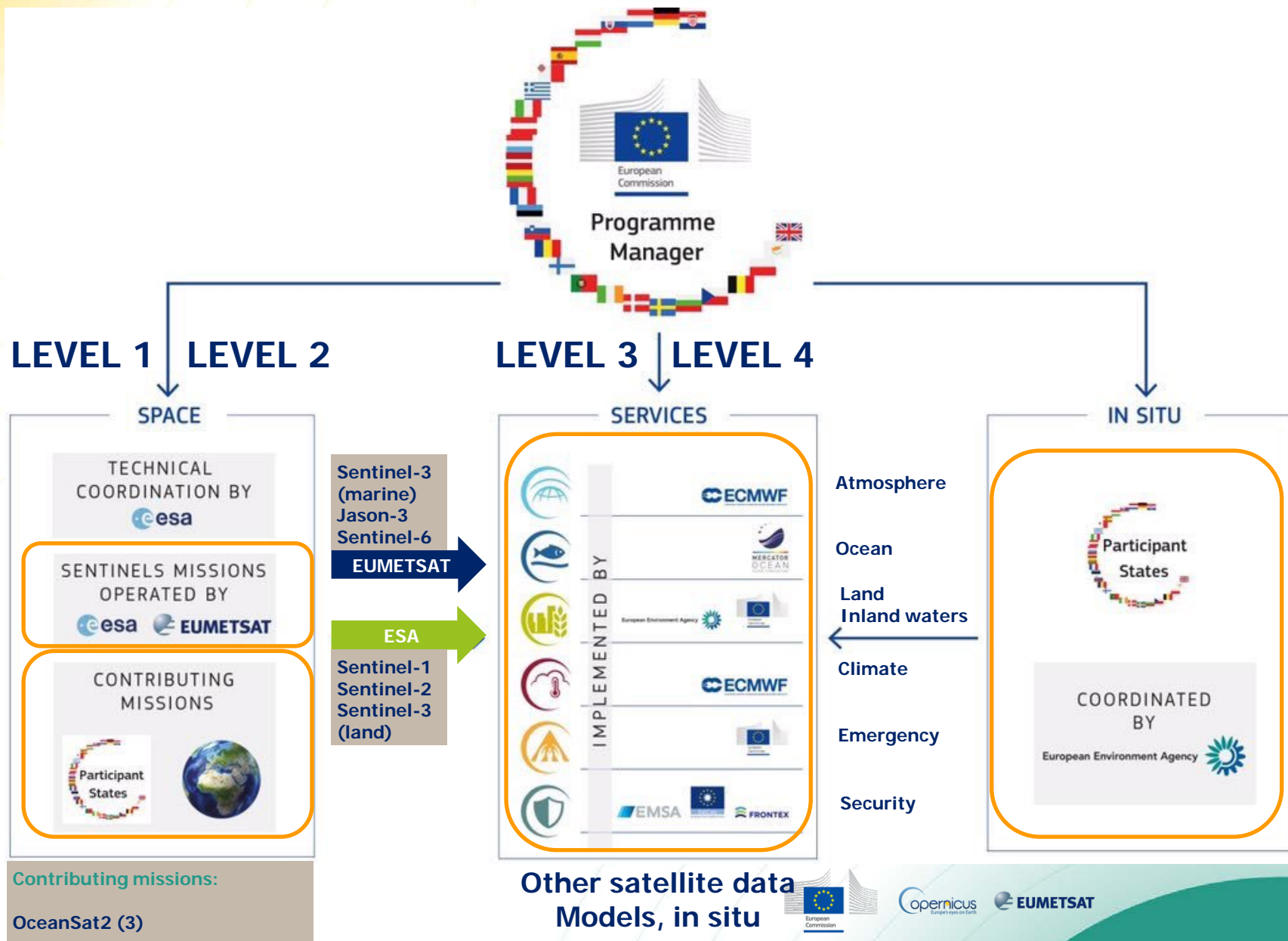
EUMETSAT

ISFRN workshop

17<sup>th</sup> September 2020



# Copernicus Ocean data



# Sentinel-3 Mission Product Responsibilities



L2 Atmosphere:  
NRT AOD & FRP



L2 Atmosphere:  
Offline AOD & FRP

L1 Global:  
OLCI full and reduced resolution  
SLSTR  
SRAL / MWR

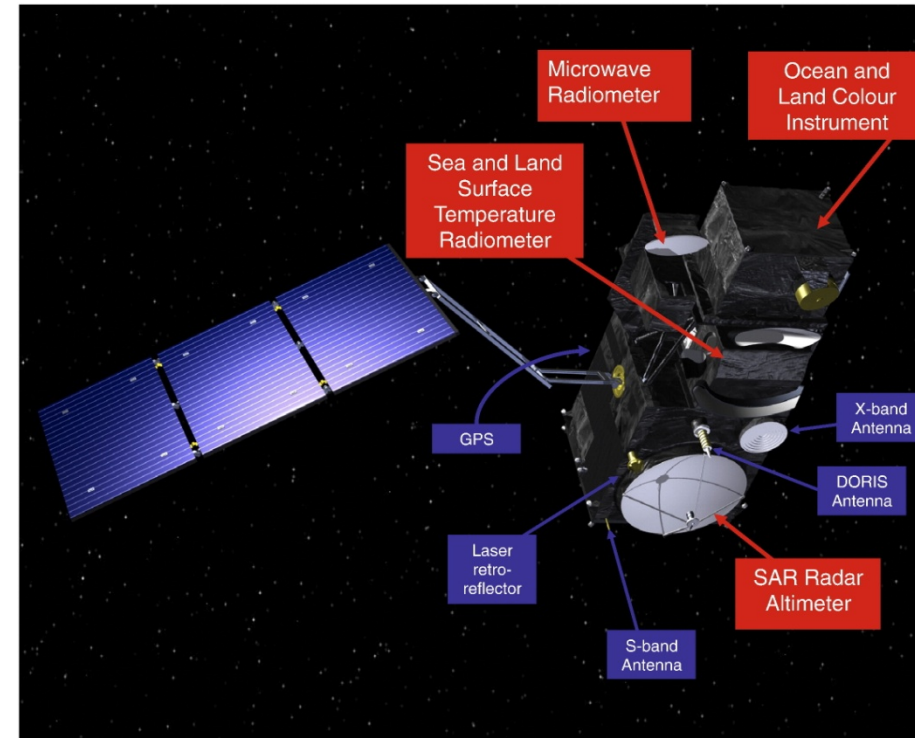
L2 Marine:  
OLCI full and reduced resolution  
SLSTR  
SRAL / MWR

L2 Land:  
OLCI full and reduced resolution  
SLSTR  
SRAL / MWR  
Synergy

# EUMETSAT Copernicus Data Services: Sentinel-3

- **Sentinel 3**
  - SLSTR (SST)
  - OLCI (Ocean Colour)
  - SRAL/MWR/POD (Surface topography/altimetry)
- Builds on heritage but with improved resolution and sensors.
- S3A (launched 16<sup>th</sup> Feb 2016), S3B (launched 25<sup>th</sup> April 2018)
- Spacecraft Operations (routine phase) and marine data processing/performance/dissemination
- Many applications for ocean research and commercial operations.

**Also operating Jason-3 (altimetry) and Sentinel-6/Jason-CS (from 2020) on behalf of European Commission.**



# Sentinel-3A and -3B

- Two satellites working together to optimize coverage.
  - 27 day repeat cycle
  - 140° phasing between A and B
  - Full global coverage in <3 days (OLCI) and <2 days (SLSTR) at the equator.
- Secondary benefit: opportunities for inter-calibration.
  - Tandem phase
  - Data available to S3VT from EUMETSAT

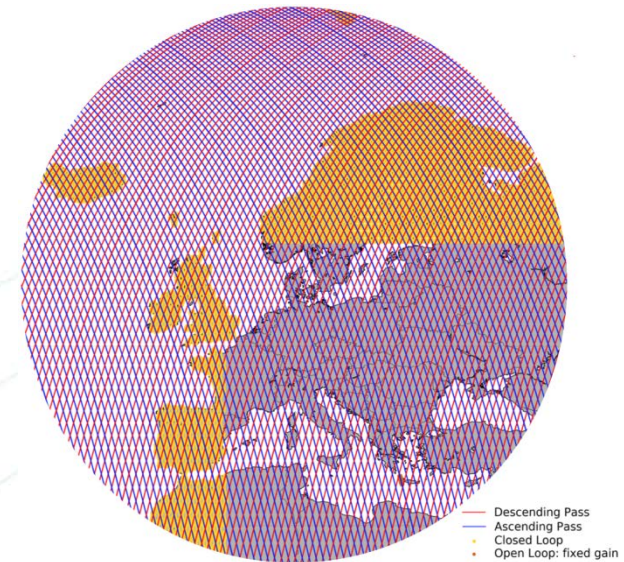
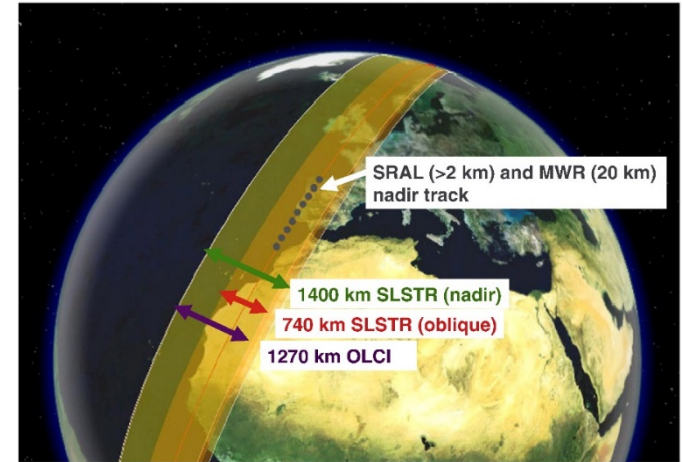
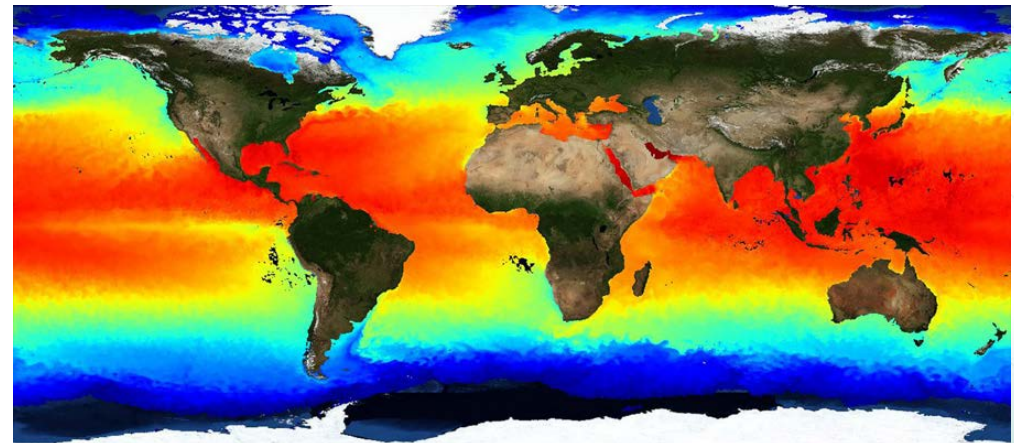


Figure 1: S3A SRAL track spacing and operating modes

# EUMETSAT Copernicus Marine Data Service

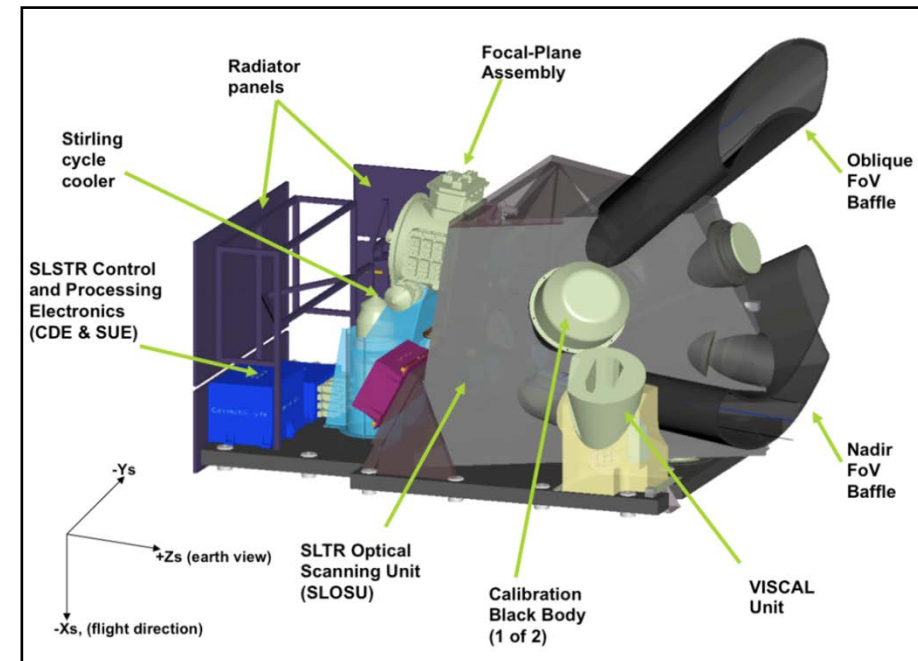
- **Sentinel-3A and 3B**
  - Operation of satellite
  - Ground segment
    - Data processing
    - Data to services
- **Global Level 1 and Marine Level 2 data**
  - Daily, highest resolution (sensor specific, native)
  - NRT/STC/NTC
  - Level 1 allows for the user to implement custom processing
  - Level 2 - geophysical products provided as standard



# Sea Surface Temperature from SLSTR

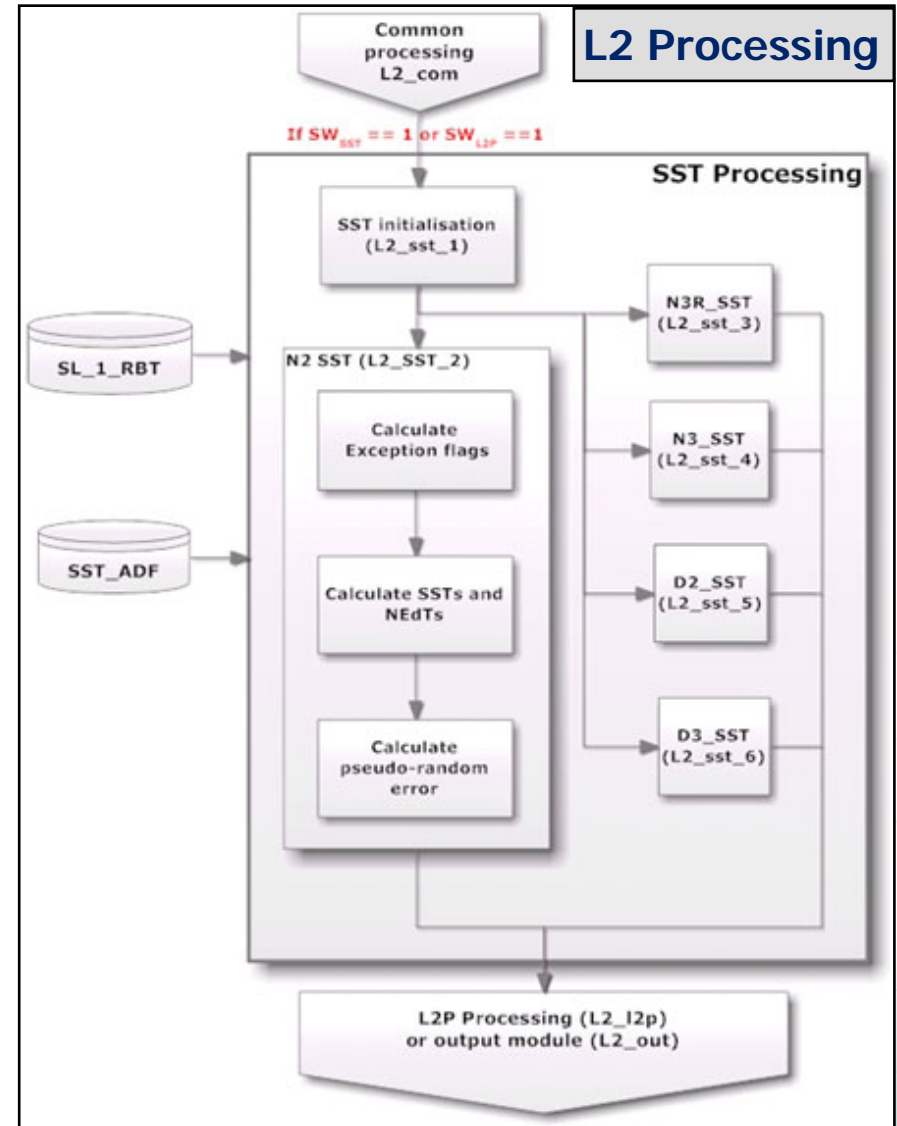
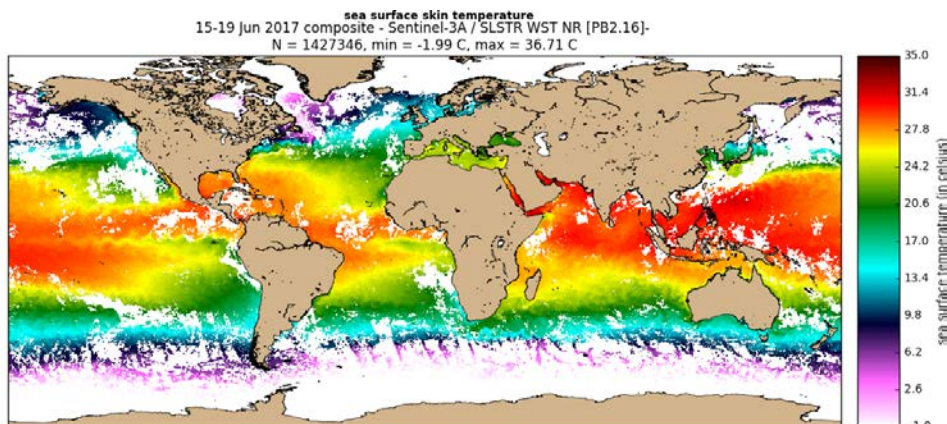
- Spatial resolution: 500 m (optical) & 1 km granules (TIR) (all L1 and L2 NRT), 500 m & 1 km full-orbit dumps (L2 NTC)
- 9 spectral bands: 6 optical, 3 TIR (S7 S8 and F1 F2, overlap)
- With S-3A and S-3B < 2 day revisit
- Daytime (descending) and nighttime (ascending) passes

Band	$\lambda$ centre ( $\mu\text{m}$ )	Width ( $\mu\text{m}$ )	Function	Comments		Res. (m)
S1	0.555	0.02	Cloud screening, vegetation monitoring, aerosol	<b>Visible Near IR (VNIR)</b>	<b>Solar reflectance bands</b>	<b>500</b>
S2	0.659	0.02	NDVI, vegetation monitoring, aerosol			
S3	0.865	0.02	NDVI, cloud flagging, Pixel co-registration			
S4	1.375	0.015	Cirrus detection over land			
S5	1.61	0.06	Cloud clearing, ice, snow, vegetation monitoring	<b>Short-Wave IR (SWIR)</b>		
S6	2.25	0.05	Vegetation state and cloud clearing			
S7	3.74	0.38	SST, LST, Active fire	<b>Thermal IR bands (TIR)</b>	<b>Thermal IR fire bands (TIRf)</b>	<b>1000</b>
S8	10.85	0.9	SST, LST, Active fire			
S9	12	1	SST, LST			
F1	3.74	0.38	Active fire	<b>Thermal IR fire bands (TIRf)</b>		
F2	10.85	0.9	Active fire			



# Sea Surface Temperature from SLSTR

- Level 1 – Radiances (S1-S6, 500 m) and brightness temperatures (S7-S9, 1 km), fire bands (F1 and F2, 1 km).
- Level 2 – GHRSSST user product L2P SST (1 km) with quality flags, meteorological parameters, single sensor error statistics, algorithm flags plus internal WCT SST (single algorithms)





# Measuring SST - Algorithms

- SLSTR has 5 algorithm for SST retrieval
- “N” only algorithms use only the nadir looking view.
- “D” algorithms combine both nadir and oblique view to give a “dual” view.
- D & N algorithms have variants that use 2 (day) or 3 channels (at night).
- Dual-view retrievals have the ability to provide a better atmospheric correction.

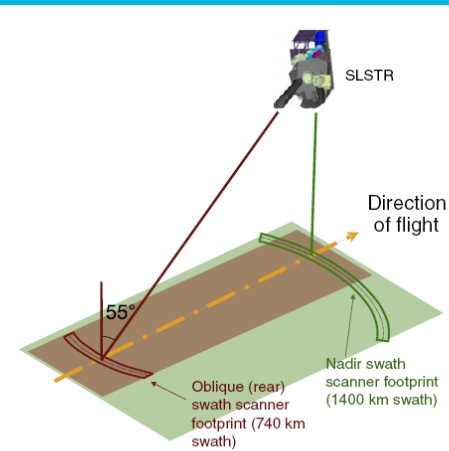
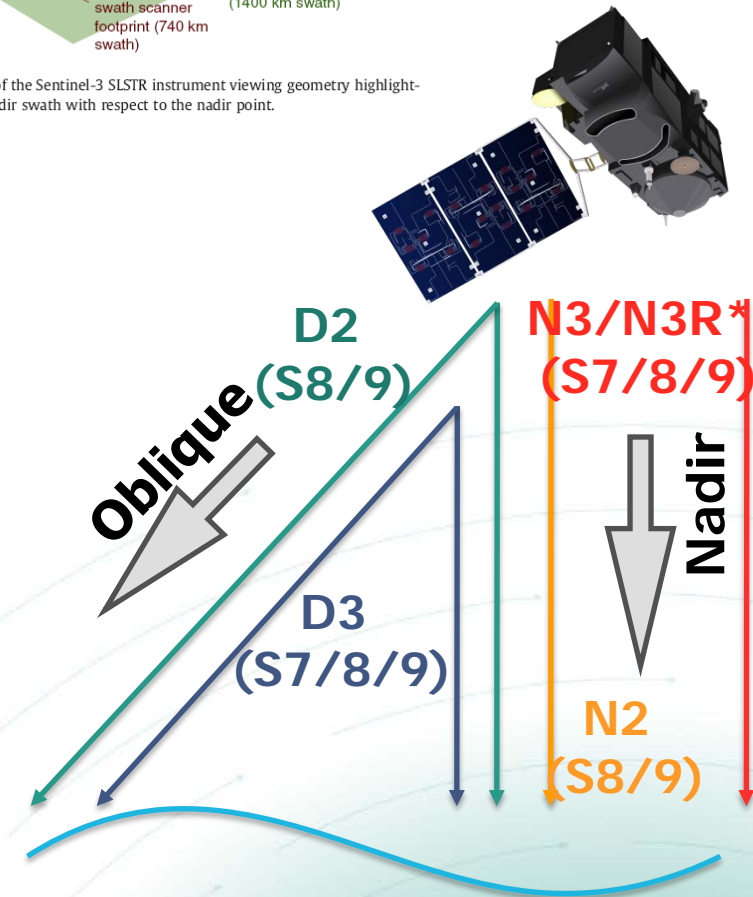
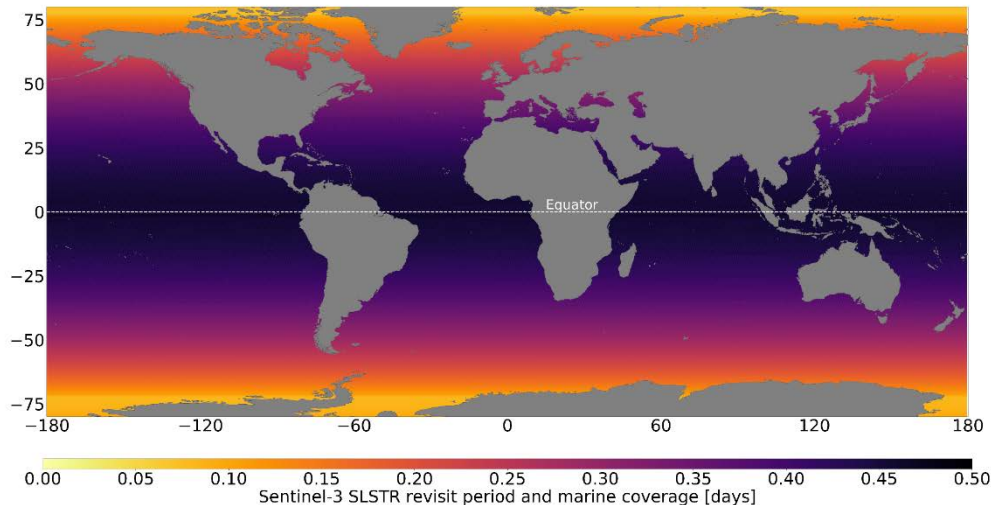
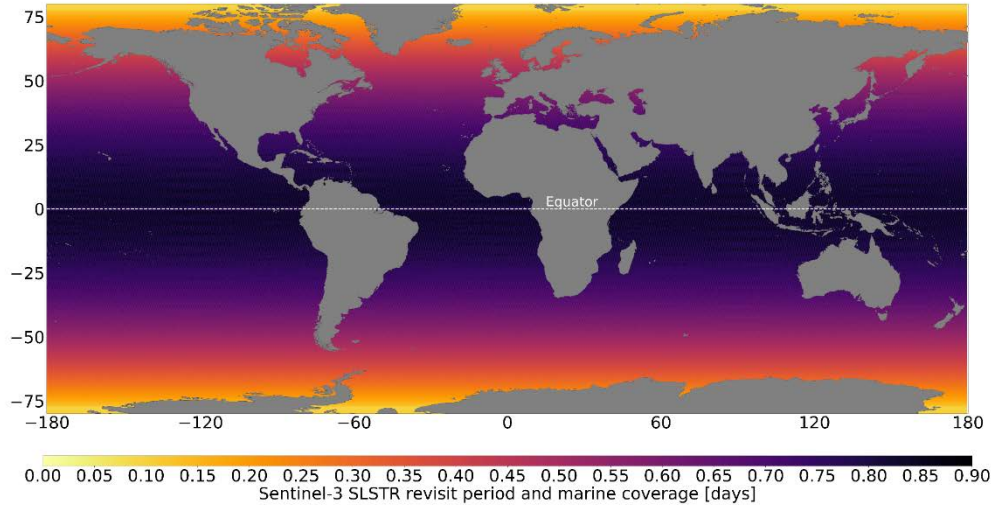


Fig. 8. Outline sketch of the Sentinel-3 SLSTR instrument viewing geometry highlighting the asymmetric nadir swath with respect to the nadir point.



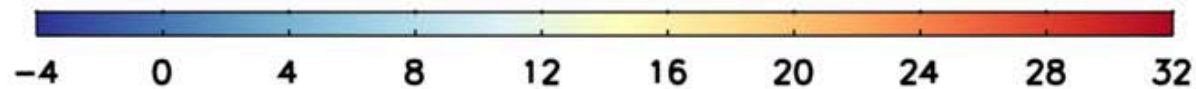
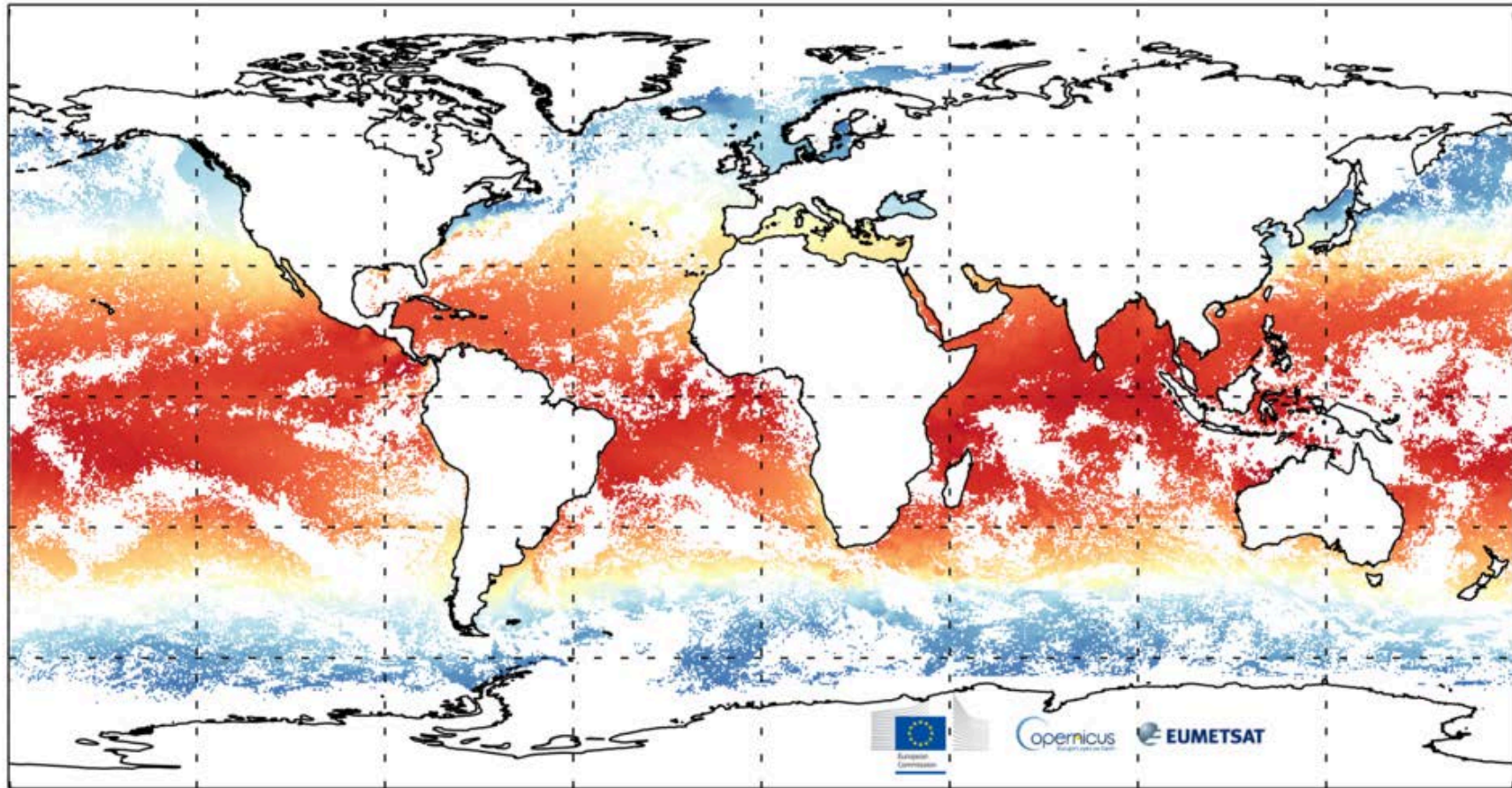
# Coverage maps – sea surface temperature (dual, top) (nadir, bottom)

- Users can consider S3A and S3B as one sensor
- Harmonisation is currently performed through the SSES, but will be refined shortly with revised retrieval coefficients



# Combined coverage: SLSTR-A & SLSTR-B – two days

Copernicus Sentinel-3 SLSTR-A and SLSTR-B SST 18-19 Mar 2019



Sea Surface Temperature (°C)

# SLSTR SST processing baseline - status

- Since 15 January 2020:
  - L1 PB -> S3A: 2.59 & S3B: 1.31
  - L2 Marine PB -> S3A: 2.61 & S3B: 1.33

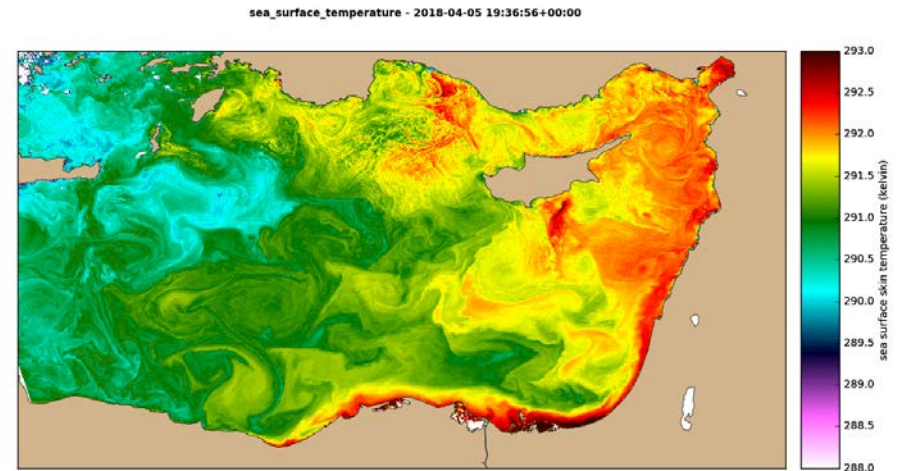
L1 major changes -> ortho-regridding, F1 channel co-registration improvement, temporal interpolation of meteorological fields, removal of S7 upper brightness temperature limit

L2 marine changes -> small Quality Level update; no major change to SST
- Since 28 May 2020:
  - L2 Marine PB -> S3A: 2.61 & S3B: 1.40

Update the SLSTR-B SSES ADF to compensate for the cold finger temperature increase that occurred on 30<sup>th</sup> March 2020. No change to SLSTR-A

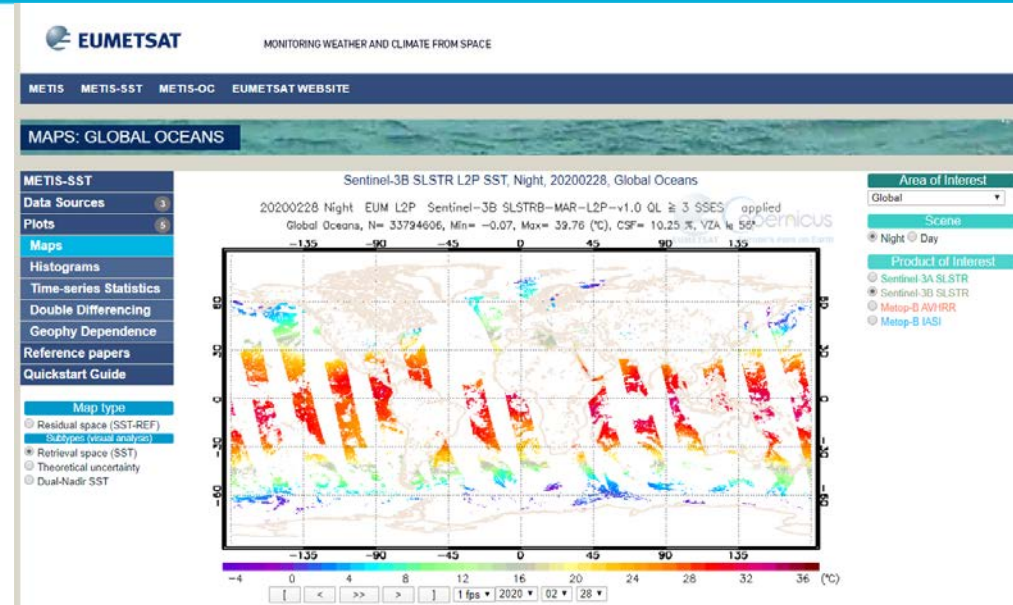
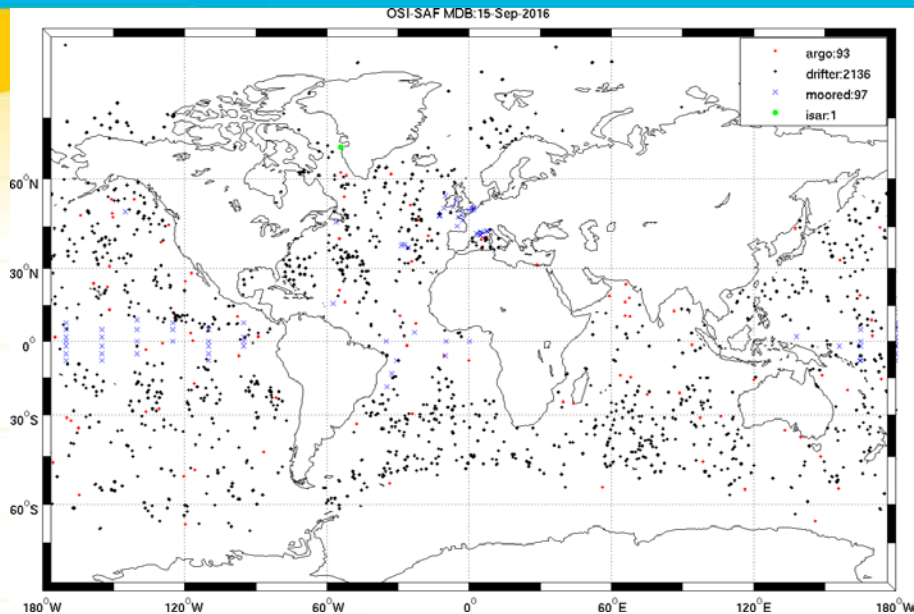
- Since 9 June 2020:
  - L1 PB -> S3A: 2.59 & S3B: 1.40

Correction of upper BT limit for the SLSTR-B S7 oblique view channel

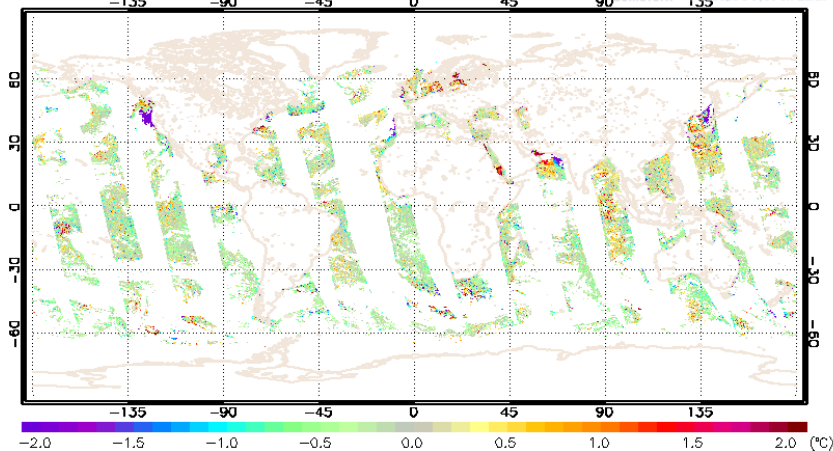


- Future plans:
  - Improvements to Bayesian cloud especially coastal zones
  - SLSTR day-2 SST: 2023

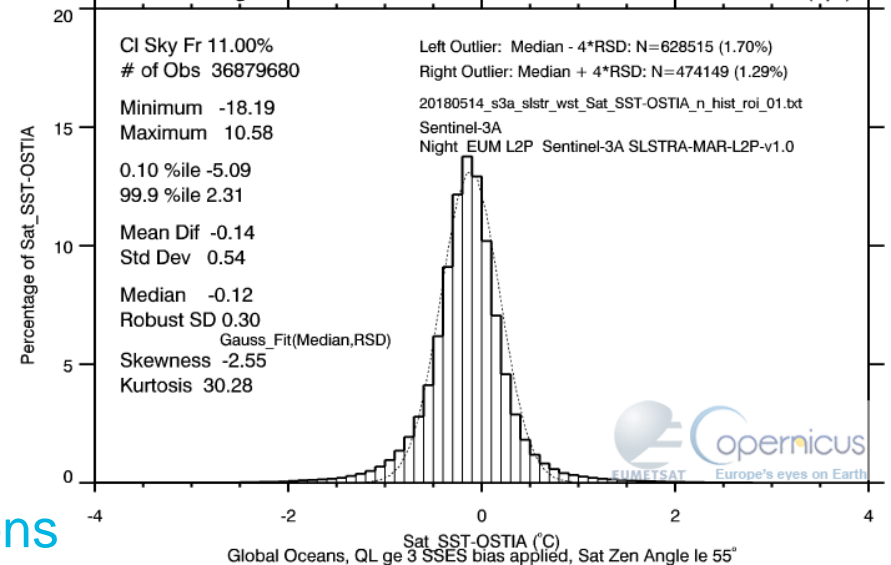
# SST validation (metis.eumetsat.int)



20180514 Night EUM L2P Sentinel-3A SLSTR-MAR-L2P-v1.0 - OSTIA (opr)  
Global Oceans, N= 36879680, Min= -18.19, Max= 10.58 (°C), outliers retained SSES



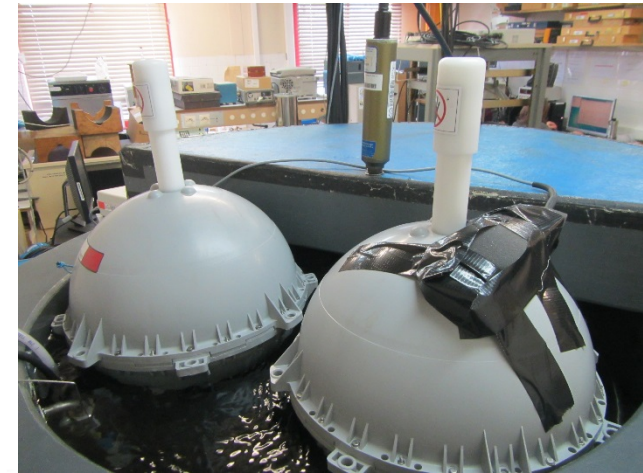
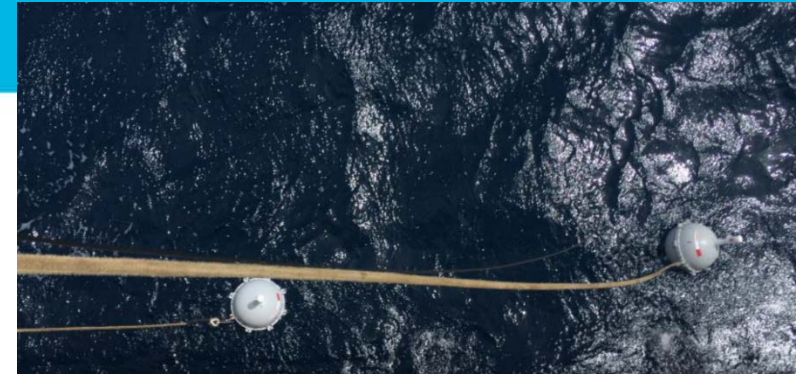
20180514 Night EUM L2P Sentinel-3A SLSTR-MAR-L2P-v1.0-OSTIA (opr)



➡ More info from Gary and Igor's presentations

# TRUSTED – Towards FRM

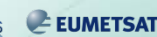
- Towards *Fiducial Reference Measurements of Sea-Surface Temperature by European drifters (TRUSTED)*
  - > Additional digital SST probe to standard SVP-B
  - > Near surface water pressure sensor.
  - > High frequency data available.
- Began January 2018 – 4 year project
  - Technical and Service Spec: SVP-BRST
  - Phase 1: verification of 2 prototype buoys
  - Phase 2: Manufacture and deployment of 100 TRUSTED drifting buoys and further 50 underway
  - Initial validation and analysis presented to WMO DBCP in October 2019
  - Preparation of TRUSTED MDB for sharing
  - TRUSTED sensor experiment on AMT 2019: W. Wimmer



Poli et al, 2019; Le Menn et al, 2019

**TRUSTED HRSST  
workshop 2-4 March**

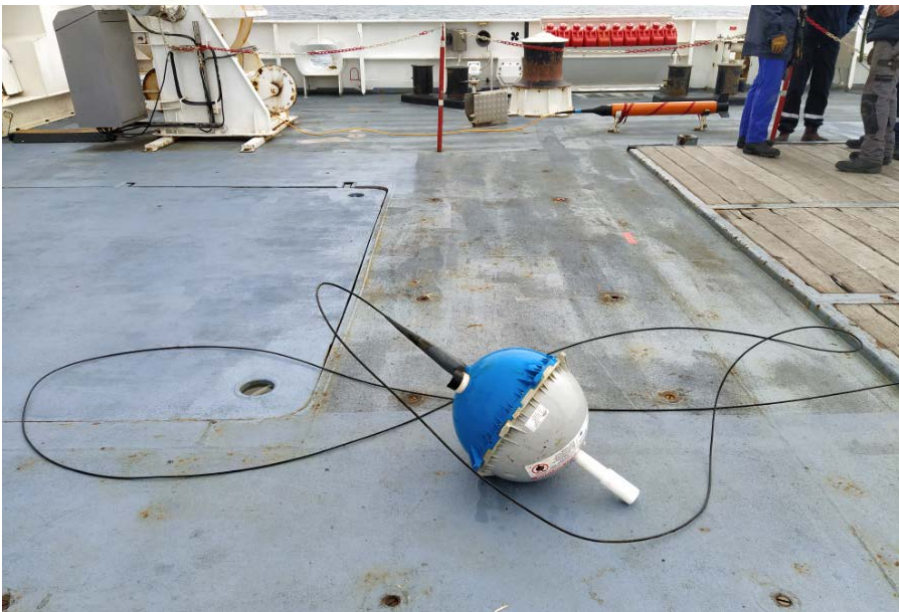
**2021**



# TRUSTED – recovery of drifting buoy 4101771

- TRUSTED buoy recovered on 8<sup>th</sup> August and is currently on a SHOM ship due back in Brest in November
- The buoy is in good condition, with the drogue lost
- The buoy was originally deployed on 20<sup>th</sup> September 2019
- The plans are that it will be re-calibrated at SHOM facilities and the uncertainty characteristics and any drift analysed.

<https://www.eumetsat.int/website/home/Data/ScienceActivities/ScienceStudies/TowardsfiducialReferencemeasUrementsofSeaSurfaceTemperaturebyEuropeanDriftersTRUSTED/index.html>



*CLS, Meteo-France,  
SHOM, BSH, NKE,  
JCOMMOPS  
(funded by Copernicus)*

# Thermal-infrared inter-comparisons

- Study to inter-compare thermal infra-red in situ and satellite datasets
- The preparation of ISAR and KIT radiometers on the car ferry MS Friedrichshafen over Lake Constance / Bodensee just started
- More info:

<https://www.eumetsat.int/website/home/Data/ScienceActivities/ScienceStudies/ThermalInfraredProductIntercomparisonandValidationwithFRMRadiometers/index.html>



*Frank Goettsche  
and Werenfrid  
Wimmer*

*(funded by  
EUMETSAT)*



# SLSTR SST: further information and product notes

## SEA SURFACE TEMPERATURE SERVICES

### SATELLITES

#### CURRENT SATELLITES

METEOSAT

METOP

SENTINEL-3

ALTIMETRY SERVICES

OCEAN COLOUR SERVICES

SEA SURFACE TEMPERATURE SERVICES

SENTINEL-3 DESIGN

SENTINEL-3 DATA FORMATS

SENTINEL-3 TOOLS & TRAINING

JASON-3

JASON-2

#### FUTURE SATELLITES

#### PAST SATELLITES

#### LAUNCHES AND ORBITS

#### GROUND SEGMENT

#### SCIENCE ACTIVITIES

#### TECHNICAL DOCUMENTS

#### GLOSSARY

### RELATED LINKS

#### VISUALISE SLSTR DATA

SLSTR GHRSSST L2P Sea Surface Temperature (SST) data can be visualised on EUMETView, our web map service.

The dual view, nine-channel Sea and Land Surface Temperature Radiometer (SLSTR) measures sea surface temperature, sea surface temperature, land surface temperature, sea-ice and land ice temperature, atmospheric aerosols, cloud properties and fire radiative power.

SLSTR continues the sea surface temperature record collected by the (A)ATSR instruments on ERS and Envisat satellites.

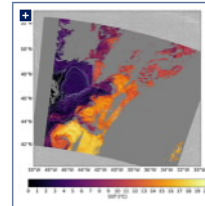
The aim is to collect highly accurate measurements to provide a reference dataset for other sea surface temperature missions on other satellites.

Sea surface temperature data is used as input for weather and ocean forecasting, to observe and monitor ocean current systems and ocean fronts, eddies, upwelling areas, marine ecosystems and the development of large scale El Niño/La Niña events.

Because of the importance of sea surface temperature to the global heat budget it is monitored as an essential climate variable (ECV).

These data are also used to improve understanding of the ocean surface layer, upper ocean variability, energy transfer, air-sea interactions and the impact of changes in the temperature of the ocean surface over the course of the day and changes between the temperature at the ocean surface and the depths below.

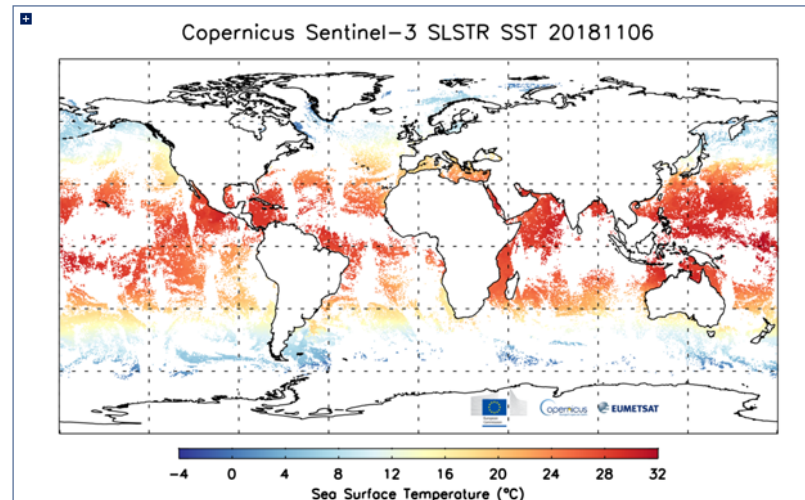
SST data is also used to help manage marine ecosystems, e.g. identifying frontal areas with large shoals of fish or monitoring coral bleaching events, and for travel and tourism.



### SLSTR PRODUCTS

The products are available in:

- Near-Real-Time (NRT): products shall be available to the users within three hours after sensing.
- Non-Time-Critical (NTC): products available to the users within one month after sensing.



[slstr.eumetsat.int](http://slstr.eumetsat.int)

- Any questions?

