

Skin Temperature Measurements for the Saildrone

Andy Jessup

Applied Physics Laboratory, University of Washington

ISFRN Workshop, 17 Sep 2020

Acknowledgements

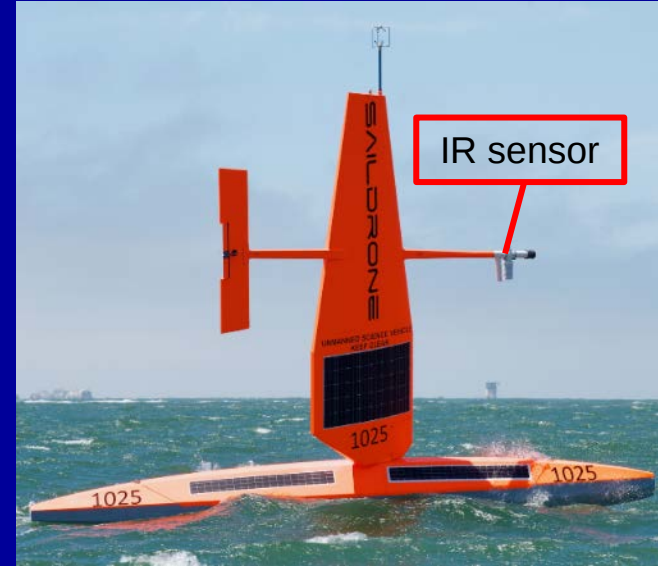
Mike Reynolds, RMR Co.

Richard Jenkins, Saildrone



Challenges for T_{skin} from saildrone

- Downlooking radiometer only
- No external calibration
- Large effective θ_{inc} range
 - Heel angles up to 40°
 - Angle varies with boom position
- Need low power, simple operation



saildrone



Calibration

- Simplify Calibration
 - Not enough power for hot BB
 - Is ambient BB only adequate?
- Use 2016 SPURS-2 ROSR data
 - Examine performance using ambient BB only
 - Suggest improved stability over past 20 years
 - Brief comparison with saildrone

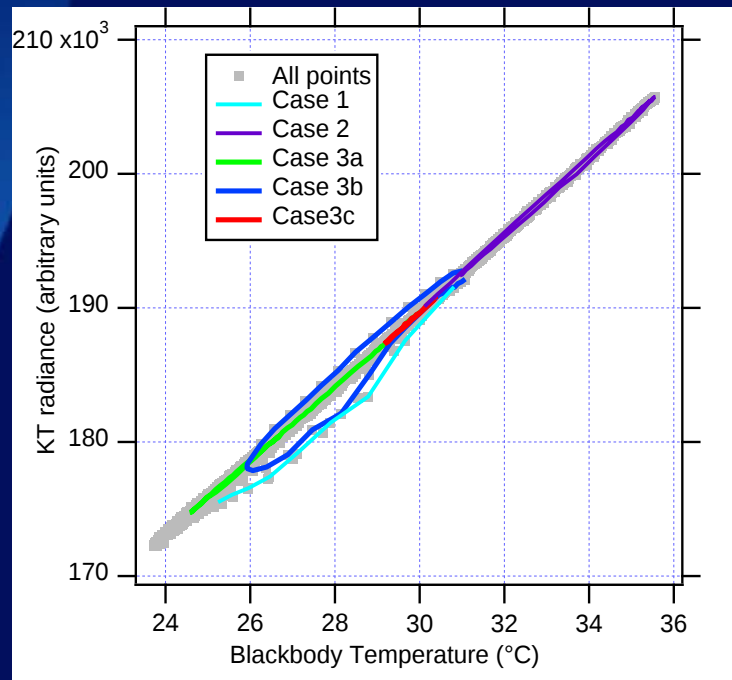
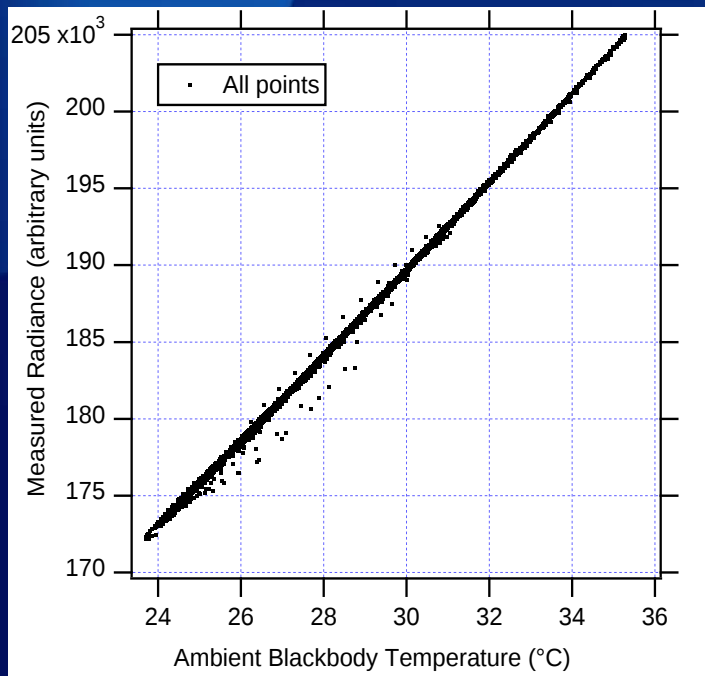


Sky Measurement

- Add separate uplooking radiometer
 - No mirror (power, weather, simplify)
 - Uncalibrated, modify lens
 - Allows better downlooking protection
- Test of bow mounted sensors in 2019
 - Chosen to mitigate additional boom angle effect
 - $\theta = 50^\circ$

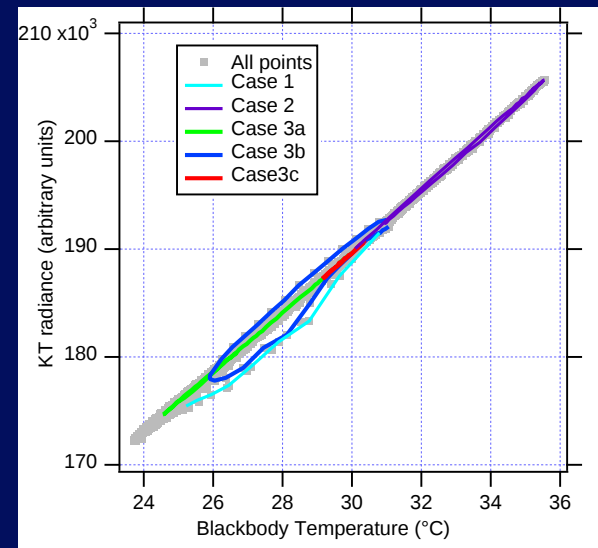
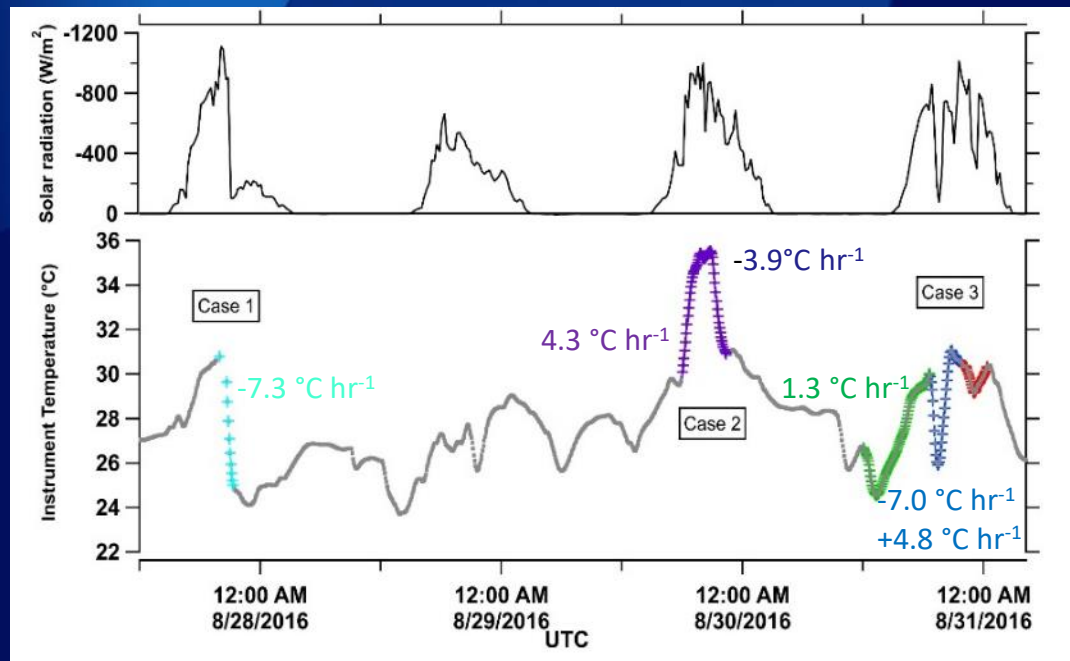


ROSR Ambient BB Calibration



SPURS-2 Cruise: 36 days, over 10,000 measurements

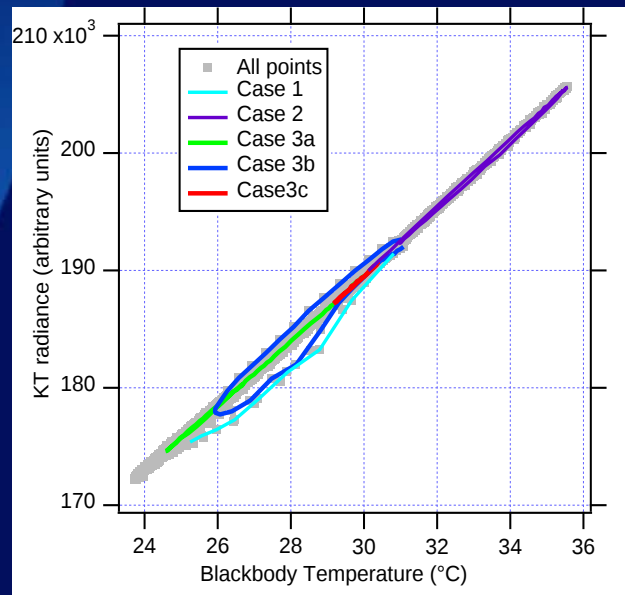
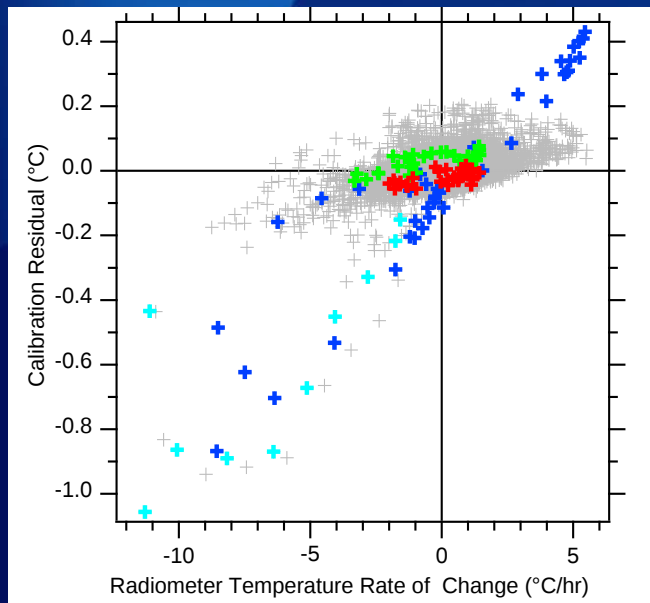
Drift with $T_{instrument}$ Rate of Change



Stable for $\pm 4.5^{\circ}C\ hr^{-1}$



Residual vs Rate of Change



Residual from linear fit to calibration data



ROSR: 1-pt vs 2-pt Calibration

SPURS-2 Cruise

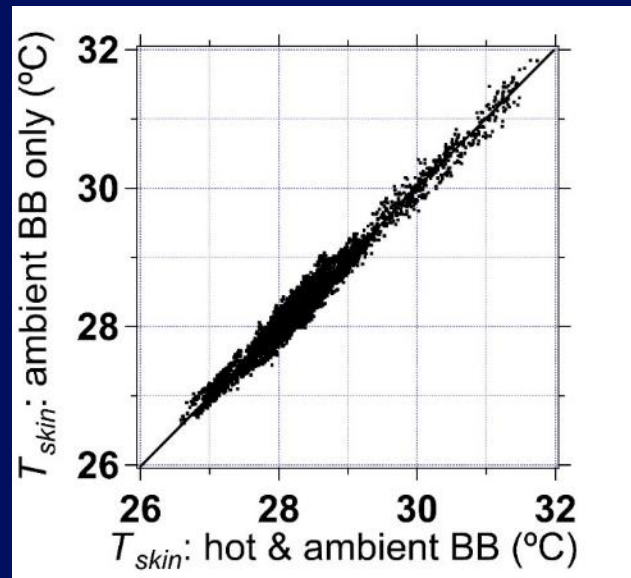
Mean difference: -0.03 °C

Std. Deviation: 0.13 °C

Minimum: -0.45 °C

Maximum: 0.42 °C

Comparable to intercomparison
of independent instruments



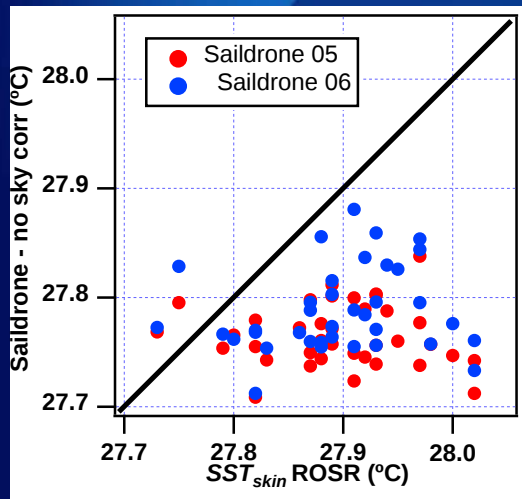
Quantity	Mean	Std dev	Min	Max
$T_{\text{ISAR}} - T_{\text{CIRIMS}}$	0.00	0.13	-0.64	0.52
$T_{\text{ISAR}} - T_{\text{MAERI}}$	-0.08	0.15	-0.84	1.01
$T_{\text{MAERI}} - T_{\text{CIRIMS}}$	0.08	0.15	-1.15	1.10

Jessup and Branch [2008]



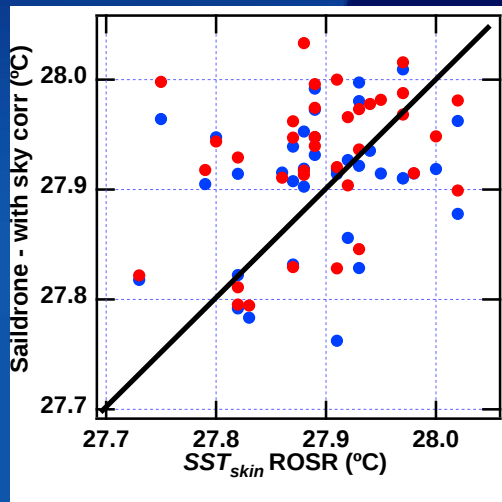
T_{skin} : Saildrone versus ROSR

T_{bright}



RMSE: 0.15 & 0.13 °C

T_{skin}

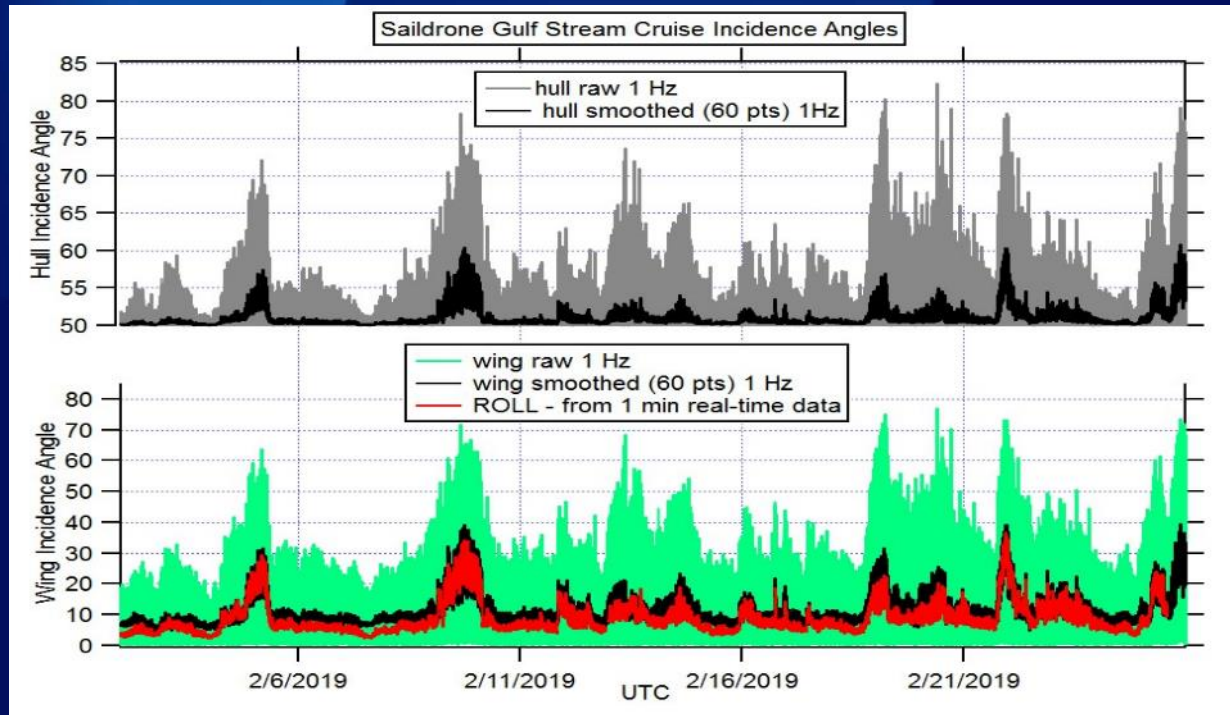


RMSE: 0.09 & 0.10 °C

- Factory calibration
- Saildrone sky correction using ROSR sky data



Effective θ_{inc} for Wing and Hull

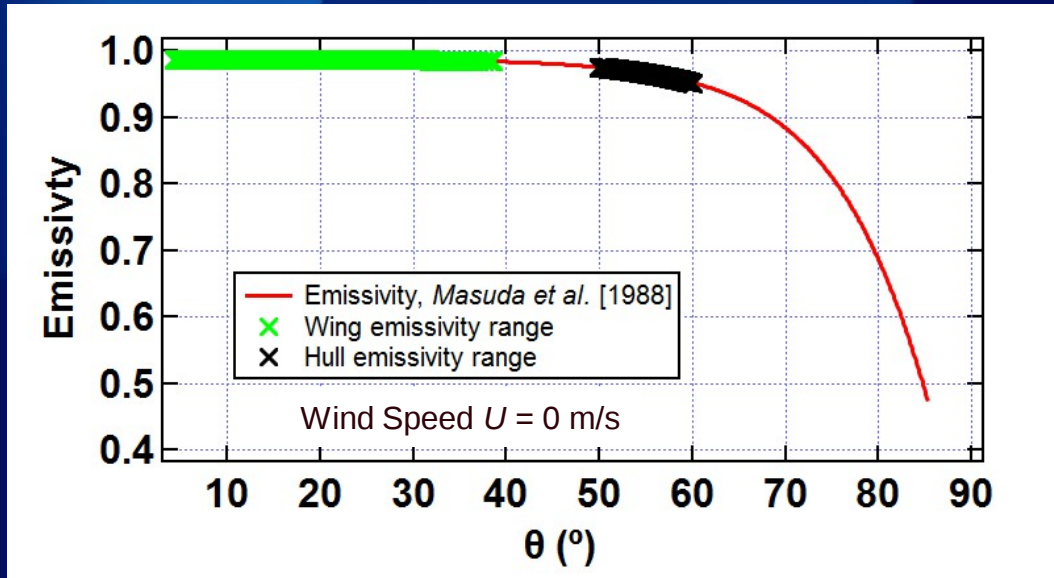


Derived
from IMU

Gulf Stream Cruise: 1 month



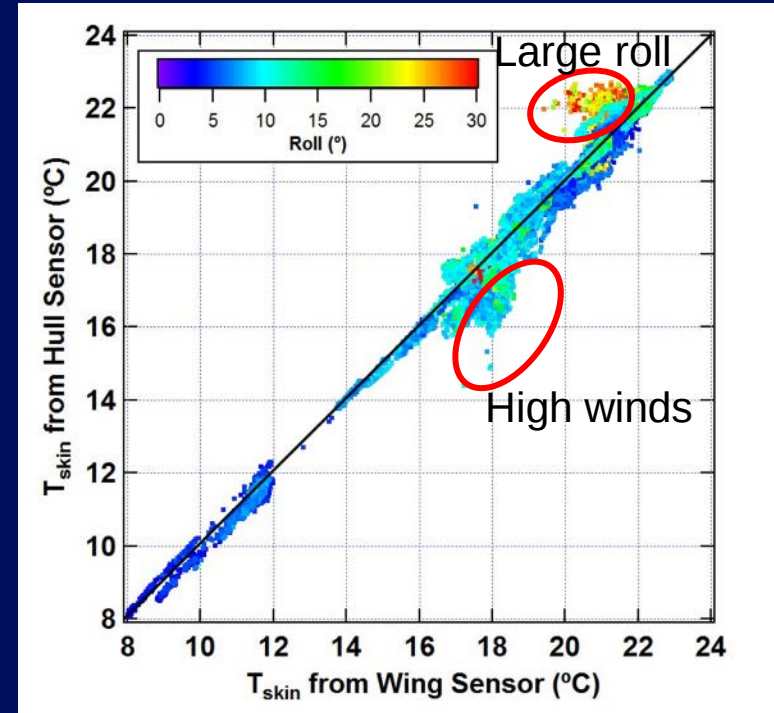
T_{skin} from Wing versus Hull



T_{skin} from Hull versus Wing

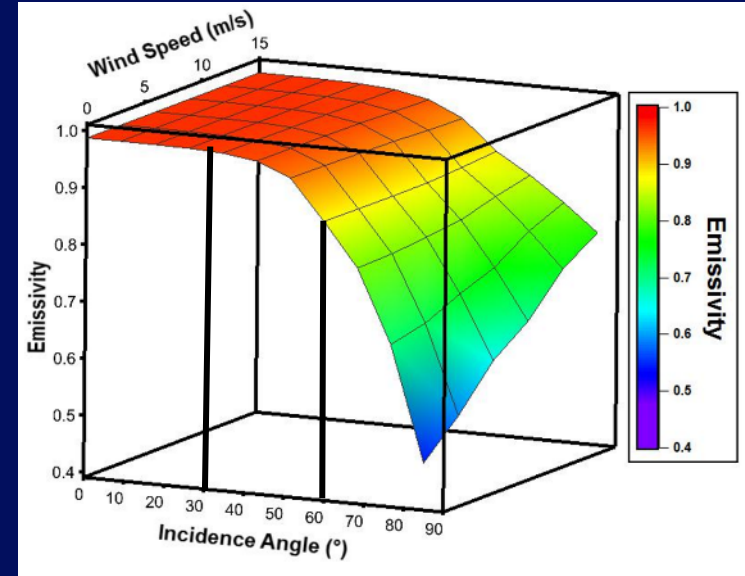
Sky correction using hull measurement

- Mean Difference: 0.08 °C
- Standard Deviation: 0.40 °C
- Greatest difference
 - Large roll
 - High wind speed
 - Likely emissivity effect



Emissivity Effects

- Decreases with θ
- Wind speed U dependence
 - 0-30° : negligible effect
 - 30-60°: decreases with U
 - > 60° : increases with U



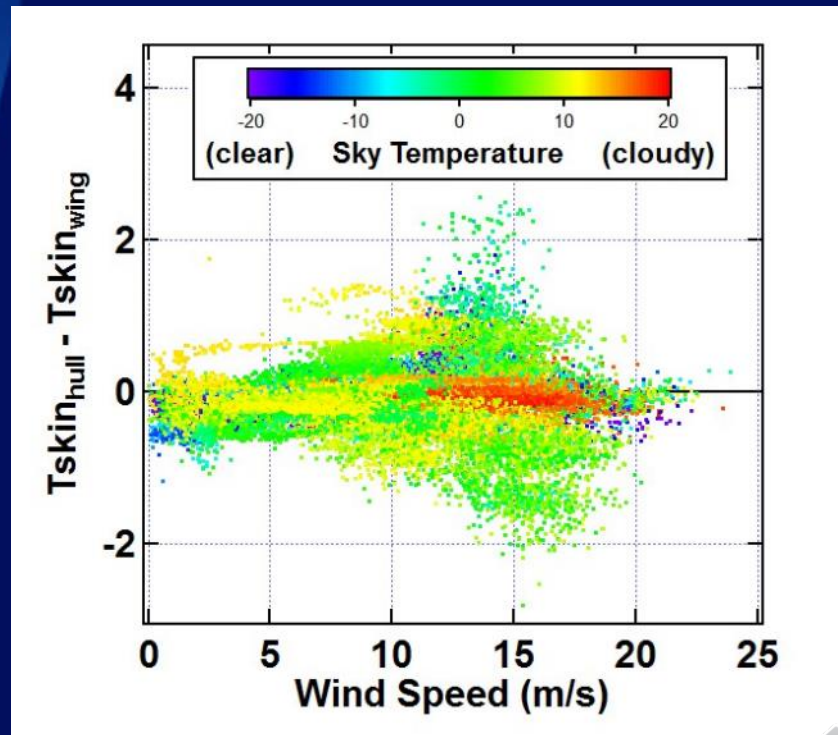
Sky Correction at High Winds

Cloudy or clear:

Minimal effect

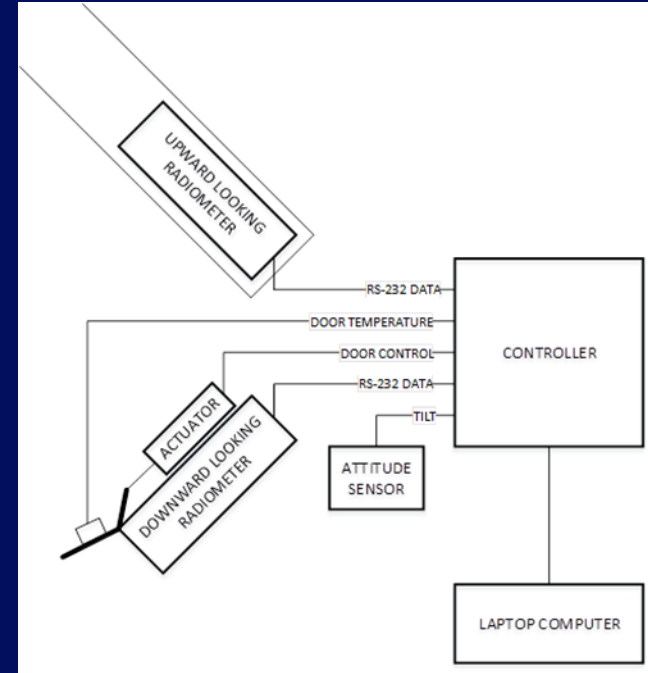
Partly cloudy:

Large +/- errors



Conclusion

- Sensor stability suggests ambient BB calibration adequate
- Housing for radiometer with door for ambient BB calibration
- Wing location minimizes heel effect due to smaller θ
- Saildrone plans to add an uplooking wing radiometer
- Prototype under development for simplified calibration system



BB on
door

